Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
Ш	49812	(detect\$3 or monitor\$3 or track\$3) near4 (boundar\$3 or space)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:38
L2	588537	(first or second) near3 (space or position or coordinat\$3)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:34
L3	69299	compar\$5 with (distance or coordinates)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:35
L4	906	1 and 2 and 3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:36
L5	7382	(predetermined or predefined or preselected) near2 (fixed near2 (position or coordinate))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:07
L6	8	4 and 5	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:37
L7	305108	(detect\$3 or monitor\$3 or track\$3) near9 (individual or person or animal or pet or object)	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 09:39
L8	288	4 and 7 and boundar\$3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:20
L12	5	8 and 5	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:07
L13	88	8 and (fixed near2 (position or coordinate))	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:13
L14	13	(("6518919") or ("6480147") or ("6441778") or ("6421001") or ("6236358") or ("6388612") or ("6362778") or ("6172640") or ("5905461")).PN.	USPAT; EPO; JPO; DERWENT	OR	OFF	2005/06/21 11:14
L15	0	14 and 7 and 5 and boundar\$3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21
L16	7	14 and 7 and boundar\$3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21
L17	6	16 and 3	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21
L18	2	17 and 2	USPAT; EPO; JPO; DERWENT	OR	ON	2005/06/21 11:21

US 5774826 A	Optimization of survey 701/207	342/357.01; 342/457; 701/213
US 6888953 B2	Optimization of survey 701/207 Vehicle surroundings 382/104	382/106; 382/154; 382/291; 701/2
US 6885771 B2	Image recognition mel 382/199	382/165; 382/203; 382/209; 382/2
US 6874420 B2	System and method fc 101/485	101/181; 101/248; 101/DIG.46; 2!
US 6804386 B1	•	·
	Optical member inspe 382/141	382/144; 382/145
US 6788804 B1	Optical member inspe 382/141	
US 6786732 B2	Toothbrush usage mo 434/263	075/4.40
US 6748015 B2	Spread spectrum rece 375/150	375/149
US 6724811 B2	Pseudo-noise correlat 375/150	375/130; 375/134; 375/137; 375/
US 6714665 B1	Fully automated iris re 382/117	382/106; 382/190; 382/209
US 6707571 B1	Character printing me 358/1.18	347/40; 358/1.11
US 6705715 B2	Liquid container, cartr 347/87	347/7; 347/86
US 6697513 B1	Optical member inspe 382/141	382/144; 382/145
US 6695747 B2	Transmission mechan 477/123	477/174; 477/97; 701/63; 74/335
US 6665439 B1	Image recognition met382/199	382/165; 382/197; 382/203; 382/2
US 6664965 B1	Image processing dev 345/473	
US 6636625 B1	Optical member inspe 382/141	382/142; 382/149
US 6633814 B2	GPS system for navig 701/213	•
US 6596983 B2	Perimetric detection s 250/221	160/7; 220/345.1; 220/345.5; 220
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US 6535627 B1	Optical member inspe 382/141	356/239.4
US 6519358 B1	Parallax calculating a ₁ 382/154	·
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US 6480285 B1	Multiple layer confoca 356/492	356/497
US 6477264 B1	Optical member inspe 382/141	382/143
US 6476909 B1	Optical member inspe 356/239.2	356/124; 356/239.1
US 6454400 B1	Liquid container, cartr 347/86	
US 6437778 B1	Virtual space commur 345/419	
US 6434263 B1	Optical member inspe 382/141	382/144; 382/145
US 6430310 B1	Optical member inspe 382/141	356/124; 359/798
US 6427023 B1	Optical member inspe 382/141	382/144; 382/145
US 6421609 B2	GPS receiver with cro 701/213	342/355; 342/357.01; 342/357.06
US 6400753 B1	Pseudo-noise correlat 375/134	375/130; 375/137; 375/140; 375/ ⁻
US 6393046 B1	Spread spectrum rece 375/134	375/130; 375/137; 375/140; 375/ [*]
US 6375306 B1	Image printing method 347/40	347/12; 358/1.9; 400/76
US 6373485 B1	Mitigating the effects (345/421	345/622
US 6370261 B1	Vehicle surroundings 382/104	382/100
US RE37610 E	Running guide appara 340/435	180/167; 340/901; 340/903; 348/
US 6363165 B1	Optical member inspe 382/141	382/144; 382/145
US 6351554 B1	Optical member inspe 382/141	356/124; 359/798; 382/144
US 6349145 B1	Optical member inspe 382/141	382/143
US 6344930 B1	Total-focus imaging a 359/666	359/820
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US 6314363 B1	Computer human met 701/120	342/36; 701/117
US 6314240 B1	Lens control apparatu 396/81	396/82; 396/87
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US 6292749 B1	GPS receiver with cro 701/213	342/355; 342/357.01; 342/357.06
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US 6236937 B1	GPS receiver with cro 701/213	342/355; 342/357.01; 342/357.06
US 6205243 B1	System and method fc 382/154	250/559.23; 356/602
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US 6195475 B1	Navigation system for 382/312	0.2700, 10.1711, 70.1700.
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US 6148097 A	Optical member inspe 382/141	382/144; 382/145
US 6125325 A	GPS receiver with cro 701/213	342/355; 342/357.01; 342/357.06
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US 5956028 A	Virtual space commur 715/757	345/419; 715/849
US 5867804 A	Method and system fo 701/120	340/961; 342/36; 342/456; 701/30
US 5798519 A	Method of and appara 250/206.1	244/3.1; 473/168
US 5614913 A	Optimization of survey 342/357.12	2
US 5574836 A	Interactive display apr 345/427	345/421; 345/9; 348/51; 715/782
US 5530420 A	Running guide appara 340/435	180/167; 340/901; 340/903; 348/°
US 5343391 A	Device for obtaining the 433/76	433/72; 433/79
US 5227985 A	Computer vision syste 702/153	345/158; 702/152
US 4975960 A	Electronic facial tracki 704/251	382/100
US 4841152 A	Continuous-resistance 250/374	250/385.1
US 4831260 A	Beam equalization m∈ 250/354.1	378/151; 976/DIG.430
US 4827436 A	Non-contact high reso 250/559.36	356/621
US 4795909 A	High performance fror 250/385.1	250/374; 250/389
US 4789235 A	Method and system fo 351/246	351/210; 434/236
US 4707608 A	Kinestatic charge det 250/389	250/336.1; 250/370.09; 250/370.
US 4580231 A	Ultrahigh resolution pl715/513	
US 4518257 A	Optical inspection sys 356/621	408/6; 409/218
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US 4319332 A	Method and apparatus 342/27	340/556; 340/557; 356/5.01

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